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IMMERSED INTERFACE FINITE ELEMENT METHOD FOR DIFFUSION PROBLEM WITH LOCALIZED TERMS

Ivan Georgiev, Juri Kandilarov

Angel Kanchev University of Ruse

Abstract: In this paper we consider the diffusion problem with local own source. A weak formulation of it is done and then the immersed interface finite element method (IIFEM) is applied for the numerical solution. For discretization in time it is used Rothe’s method with weights, and then the special basis functions, which fulfill the jump conditions on the interface, are introduced. Numerical results, confirming second order of accuracy in maximum norm, are presented.

Keywords: immersed interface, finite element method, diffusion equation, local sources, Rothe’s method

INTRODUCTION

Let us consider the following parabolic problem with discontinuous coefficients and local own source:

\[ u_t(x,t) - (\beta u_x(x,t))_x + q(x,t)u(x,t) = f(x,t) - g(u(x,t))\delta(x-x_0) \quad (x,t) \in Q_T = \Omega \times (0,1] \]

with initial and boundary conditions

\[ u(x,0) = u_0(x), \]
\[ u(0,t) = u_L(t), \quad u(1,t) = u_R(t). \]

Here \( \Omega = (0,1) \), the functions \( q, f \) and \( g \) are continuous in \( \overline{Q_T} \setminus \Gamma_T \), \( \Gamma_T = \{\zeta\} \times [0,1] \), \( \delta \) is the Dirac-delta function, \( 0 < \zeta < 1 \) and \( \beta \) is piecewise continuous of the form

\[ \beta(x) = \begin{cases} 
\beta^-(x), & 0 \leq x \leq \zeta, \\
\beta^+(x), & \zeta \leq x \leq 1.
\end{cases} \]

Under some assumption of smoothness of the solution the problem (1)-(2) can be rewritten in the classical way [9] as follows:

\[ u_t(x,t) - (\beta u_x(x,t))_x + q(x,t)u(x,t) = f(x,t) \quad (x,t) \in Q_T = \Omega \times (0,1]) \]

with initial and boundary conditions (2) and jump conditions on the interface \( \Gamma_T \)

\[ [u(x,t)]_{x=\zeta} = u(\zeta^+, t) - u(\zeta^-, t) = 0 \]
\[ [\beta u_x(x,t)]_{x=\zeta} = \beta^+ u_x(\zeta^+, t) - \beta^- u_x(\zeta^-, t) = g(u(\zeta^+, t)) \]
tence and uniqueness of the variety of elliptic and parabolic interface problems are discussed in the book [9]. Special difference schemes for such problems are considered [4].

In this paper the IIFEM is applied for the proposed problem. IIFEM for interface problems with homogeneous interface conditions, or jump conditions, that are known functions, have been studied in [5-7]. In our problem the jump of the flux at the interface depends on the unknown solution. For elliptic problems of this type an IIFEM is studied in [2].

The paper is organized as follows. In the next section the weak formulation of the problem is given. Then using Rothe’s method combined with the method of weights the semi-discretization in time is done. IIFEM is applied for approximation in space. Numerical experiments are presented in the last section.

**WEAK FORMULATION OF THE PROBLEM**

Let for simplicity consider the case of linear own source, i.e. \( g(u(x,t)) = K(t)u(x,t) \), where \( K(t) > 0, \forall t \in [0,1] \) is a continuous function.

Let introduce the usual Sobolev space \( H^1(0,1) \), the bilinear form

\[
a(u,v) = \int_0^1 (\beta(x)u'_x(x,t)v'(x) + q(x,t)u(x,t)v(x)\,dx + K(t)u(\zeta,t)v(\zeta,t) \tag{5}
\]

and linear form

\[
b(f,v) = \int_0^1 f(x,t)v(x)\,dx. \tag{6}
\]

With \( (u_t(x,t),v) = \int_0^1 u_t(x,t)v(x)\,dx \) we denote the inner product in the space \( L^2(0,1) \).

Then, the weak solution of the problem (3), (4) is the function \( u \in H^1(0,1), \forall t \in (0,1) \), such that

\[
(u_t,v) + a(u,v) = b(f,v) \quad \forall v \in H^1(0,1), \tag{7}
\]

and \( u(x,t) \) satisfies the conditions in (2).

Using energetic method, see Chapter 1 of [9], it has been proved that if \( u_0(x), q, f \in L^2(0,1) \), then the solution of (3)-(4) is unique \( u \in H^1(0,1), \forall t \in (0,1) \) satisfying the weak problem (7).

**METHOD OF WEIGHTS**

Let introduce an uniform mesh in the time \( t \in [0,1] \) with constant time step \( \tau = 1/M \), \( t_m = m\tau, \ m=0,\ldots,M \), where \( M \) is a positive integer. Let also with \( z_m(x) \) denote the numerical approximation of \( u(x,t_m) \) on the \( m \)-th time layer \( m=1,\ldots,M \), and \( \sigma, \sigma \in [0,1] \) is a weight. Then the semi-discretization of the problem in time [8] looks as follows:
\[
\frac{z_m(x) - z_{m-1}(x)}{\tau} - (\sigma f z_m(x))' - (1-\sigma) q(x, t_m) z_m(x) + (1-\sigma) q(x, t_{m-1}) z_{m-1}(x) \\
= \sigma f(x, t_m) + (1-\sigma) f(x, t_{m-1}) - \sigma \delta(x-\zeta) K(t_m) z_m(x) - (1-\sigma) \delta(x-\zeta) K(t_{m-1}) z_{m-1}(x), \quad x \in (0,1)
\]

for \( m=1,\ldots,M \), initial and boundary conditions

\[
\begin{align*}
    u(x,0) &= z_0(x) = u_0(x), \\
    u(0,t_m) &= z_m(0) = u_J(t_m), \\
    u(1,t_m) &= z_m(1) = u_R(t_m),
\end{align*}
\]

and jump conditions on the interface

\[
[z_m(x)]_{x=\zeta} = z_m(\zeta^+) - z_m(\zeta^-) = 0,
\]

\[
[\beta z_m(x)]_{x=\zeta} = \beta^+ \frac{\partial z_m}{\partial x}(\zeta^+) - \beta^- \frac{\partial z_m}{\partial x}(\zeta^-) = K(t_m) z_m(\zeta).
\]

**IMMERSED INTERFACE FINITE ELEMENT METHOD**

Next we introduce uniform mesh in space direction \( x, \ x_i = ih, i = 0,\ldots,N, \) with \( h = 1/N \). Let \( J \) be the number, for which \( x_j \leq \zeta < x_{J+1} \). Let \( c_i^m \) are the unknown coefficients at \( x_i \) and \( t_m \). Then from the idea of the FEM the numerical solution on every time layer \( m \) is a linear combination \( z^h_m = \sum_{i=0}^{N} c_i^m \phi_i(x) \) of standard basic functions \( \phi_i \), \( i \neq J, i \neq J+1 \):

\[
\phi_i(x) = \begin{cases} 
\frac{x - x_{i-1}}{h}, & x_{i-1} \leq x < x_i \\
\frac{x_{i+1} - x}{h}, & x_i \leq x \leq x_{i+1} \\
0, & \text{elsewhere}
\end{cases}
\]

and two modified basis functions \( \phi_J \) and \( \phi_{J+1} : \)

\[
\phi_J(x) = \begin{cases} 
0, & 0 \leq x < x_{J-1} \\
\frac{x - x_{J-1}}{h} \alpha_1 x + \beta_1, & x_{J-1} \leq x < x_J \\
\frac{x_J - x}{h} \alpha_1 x + \beta_1, & x_J \leq x < \zeta \\
\frac{x - x_{J+1}}{h} \alpha_2 x + \beta_2, & \zeta \leq x < x_{J+1} \\
\frac{x_{J+1} - x}{h} \alpha_2 x + \beta_2, & x_{J+1} \leq x \leq 1
\end{cases}
\]

\[
\phi_{J+1}(x) = \begin{cases} 
0, & 0 \leq x < x_J \\
\frac{x - x_J}{h} \alpha_1 x + \beta_1, & x_J \leq x < \zeta \\
\frac{x - x_{J+1}}{h} \alpha_2 x + \beta_2, & \zeta \leq x < x_{J+1} \\
\frac{x_{J+1} - x}{h} \alpha_2 x + \beta_2, & x_{J+1} \leq x \leq 1
\end{cases}
\]
The coefficients $\alpha_{ij}$ and $\beta_{ij}$, $i, j = 1, 2$ must satisfy the following systems of linear algebraic equations (SLAE)

\[
\begin{align*}
| \alpha_{11} x_j + \beta_{11} &= 1 \\
| \alpha_{12} x_{j+1} + \beta_{12} &= 0 \\
| \alpha_{12} \xi + \beta_{12} - \alpha_{11} \xi - \beta_{11} &= 0 \\
| \alpha_{12} - \alpha_{11} &= K(\alpha_{11} \xi + \beta_{11})
\end{align*}
\]

and

\[
\begin{align*}
| \alpha_{21} x_j + \beta_{21} &= 0 \\
| \alpha_{22} x_{j+1} + \beta_{22} &= 1 \\
| \alpha_{22} \xi + \beta_{22} - \alpha_{21} \xi - \beta_{21} &= 0 \\
| \alpha_{22} - \alpha_{21} &= K(\alpha_{21} \xi + \beta_{21})
\end{align*}
\]

Its solutions are:

\[
\begin{align*}
\alpha_{11} &= -\frac{1 + K \rho_i + x_{j+1}}{h + K \rho_i \rho_{i+1}}, \quad \beta_{11} = \frac{K \zeta \rho_i + x_{j+1}}{h + K \rho_i \rho_{i+1}}, \quad \alpha_{12} = -\frac{1}{h + K \rho_i \rho_{i+1}}, \quad \beta_{12} = \frac{x_{j+1}}{h + K \rho_i \rho_{i+1}} \\
\alpha_{21} &= \frac{1}{h + K \rho_i \rho_{i+1}}, \quad \beta_{21} = -\frac{x_j}{h + K \rho_i \rho_{i+1}}, \quad \alpha_{22} = \frac{1 + K \rho_i}{h + K \rho_i \rho_{i+1}}, \quad \beta_{22} = -\frac{K \zeta \rho_i + x_j}{h + K \rho_i \rho_{i+1}} \\
\rho_i &= \zeta - x_j, \quad \rho_{i+1} = x_{j+1} - \zeta.
\end{align*}
\]

In what follows, instead of $(,)$ for the scalar product we will use the notation $\langle , \rangle$, i.e. $<u, v> = \int_0^1 uv \, dx$. Then we multiply the semi-discrete equation (8) by the test function $v \in H^1(0,1)$, and integrating by parts with respect to $x$ we get for $j = 1, ..., N$:

\[
\begin{align*}
&\langle \sum_{m=0}^N \sigma \beta_i^m \phi_i^m, \phi_j^m \rangle + \langle \sum_{m=0}^N (1 + \sigma \xi) \beta_i^{m-1} \phi_i^{m-1}, \phi_j^m \rangle + \langle \sum_{m=0}^N (\sigma K(t_m) \xi) \phi_i^m(\zeta) \rangle \phi_j^m(\zeta) = \\
&\langle \sum_{m=0}^N \frac{1}{t} c_i^{m-1} \phi_i^m, \phi_j^m \rangle - \langle \sum_{m=0}^N (1 - \sigma) \beta_i^{m-1} \phi_i^{m-1}, \phi_j^m \rangle + \langle \sum_{m=0}^N (1 - \sigma) q \beta_i c_i^{m-1} \phi_i^{m-1}, \phi_j^m \rangle + \\
&\langle \sigma f(x, t_m), \phi_j^m \rangle + \langle (1 - \sigma) f(x, t_m), \phi_j^m \rangle = -\sum_{m=0}^N (1 - \sigma) K(t_{m-1} c_i^{m-1} \phi_i^{m-1}(\zeta) \phi_j^m(\zeta).
\end{align*}
\]

This SLAE can be presented in the matrix form as

\[
(A^1 + A^2 + A^3) c^m = (B^1 + B^2 + B^3 + B^4) c^{m-1} + (D^1 + D^2),
\]

where $c^{m-1} = (c_0^{m-1}, c_1^{m-1}, ..., c_N^{m-1})^T$ and $c^m = (c_0^m, c_1^m, ..., c_N^m)^T$ are vectors of the solution on the two consecutive time layers, with $C^0 = (c_0^0, c_1^0, ..., c_N^0)^T$, $c_i^0 = u_0(x_i)$, $c_0^m = u(0,t_m)$, $c_N^m = u(1,t_m)$ - initial and boundary conditions. The elements of the other matrices are as follows:
\[
A_i^j = \begin{cases}
0 & i \neq j, i \neq j \pm 1 \\
\sigma \int_{x_{i-1}}^{x_i} \beta^-(x) \phi_i^m(x) \phi_j^m(x) \, dx & i = j \pm 1 \text{ or } i = j, \text{ and } i < J \\
\sigma \int_{x_{i-1}}^{x_i} \beta^+(x) \phi_i^m(x) \phi_j^m(x) \, dx & i = j \pm 1 \text{ or } i = j, \text{ and } i > J + 1
\end{cases}
\]

\[
A_j^i = \begin{cases}
0 & i \neq j, i \neq j \pm 1 \\
\int_{x_{i-1}}^{x_i} \left( \frac{1}{\tau} + \alpha^-(x, t_m) \right) \phi_i^m(x) \phi_j^m(x) \, dx & i = j \pm 1 \text{ or } i = j, \text{ and } i < J \\
\int_{x_{i-1}}^{x_i} \left( \frac{1}{\tau} + \alpha^+(x, t_m) \right) \phi_i^m(x) \phi_j^m(x) \, dx & i = j \pm 1 \text{ or } i = j, \text{ and } i > J + 1
\end{cases}
\]

\[
A_{ij}^3 = \begin{cases}
\sigma K(t_m) \phi_j^m(\zeta) \phi_j^m(\zeta) & i = J, j = J \\
\sigma K(t_m) \phi_j^m(\zeta) \phi_j^m(\zeta) & i = J, j = J + 1 \\
\sigma K(t_m) \phi_j^m(\zeta) \phi_j^m(\zeta) & i = J + 1, j = J \\
\sigma K(t_m) \phi_j^m(\zeta) \phi_j^m(\zeta) & i = J + 1, j = J + 1 \\
0 & \text{other cases}
\end{cases}
\]
\[
B_{ij}^1 = \begin{cases}
0 & i \neq j, i \neq j \pm 1 \\
\int_{x_{j-1}}^{x_j} \frac{1}{\tau}(\phi_j^{m-1}(x)\phi_j^m(x))dx & i = j \pm 1 \text{ or } i = j, \text{ and } i < J \\
\int_{x_{j-1}}^{x_j} \frac{1}{\tau}(\phi_j^{m-1}(x)\phi_j^m(x))dx & i = j \pm 1 \text{ or } i = j, \text{ and } i > J + 1
\end{cases}
\]

\[
B_{ij}^2 = \begin{cases}
-\left(1 - \sigma\right) \int_{x_{j-1}}^{x_j} \beta^-(x)\phi_j^{m-1}(x)\phi_j^m(x)'dx & i = j \pm 1 \text{ or } i = j, \text{ and } i < J \\
-\left(1 - \sigma\right) \int_{x_{j-1}}^{x_j} \beta^+(x)\phi_j^{m-1}(x)\phi_j^m(x)'dx & i = j \pm 1 \text{ or } i = j, \text{ and } i > J + 1
\end{cases}
\]

\[
B_{ij}^3 = \begin{cases}
0 & i \neq j, i \neq j \pm 1 \\
\left(1 - \sigma\right) \int_{x_{j-1}}^{x_j} q^-(x, t_{m-1})\phi_j^{m-1}(x)\phi_j^m(x)dx & i = j \pm 1 \text{ or } i = j, \text{ and } i < J \\
\left(1 - \sigma\right) \int_{x_{j-1}}^{x_j} q^+(x, t_{m-1})\phi_j^{m-1}(x)\phi_j^m(x)dx & i = j \pm 1 \text{ or } i = j, \text{ and } i > J + 1
\end{cases}
\]

\[
B_{ij}^4 = \begin{cases}
\left(1 - \sigma\right) \int_{x_{j-1}}^{x_j} q^-(x, t_{m-1})\phi_j^{m-1}(x)\phi_j^m(x)dx & i = j \pm 1 \text{ or } i = j, \text{ and } i < J \\
\left(1 - \sigma\right) \int_{x_{j-1}}^{x_j} q^-(x, t_{m-1})\phi_j^{m-1}(x)\phi_j^m(x)dx & i = j \pm 1 \text{ or } i = j, \text{ and } i > J + 1
\end{cases}
\]
\[ B^4_{ij} = \begin{cases} 
- (1 - \sigma) K(t_{m-l}) \phi_j^{m-1}(\zeta) \phi_j^m(\zeta) & i = J, j = J \\
- (1 - \sigma) K(t_{m-l}) \phi_j^{m-1}(\zeta) \phi_j^{m+1}(\zeta) & i = J, j = J + 1 \\
- (1 - \sigma) K(t_{m-l}) \phi_j^{m+1}(\zeta) \phi_j^{m+2}(\zeta) & i = J + 1, j = J \\
- (1 - \sigma) K(t_{m-l}) \phi_j^{m+1}(\zeta) \phi_j^{m+2}(\zeta) & i = J + 1, j = J + 1 \\
0 & \text{other cases} 
\end{cases} \]

\[ \begin{align*}
D^1_i &= \begin{cases} 
\sigma \int_{x_{i-1}}^{x_i} f^-(x,t_m) \phi_j^m dx + \sigma \int_{x_i}^{x_{i+1}} f^+(x,t_m) \phi_j^m dx & i = J \\
\sigma \int_{x_{i-1}}^{x_i} f^-(x,t_m) \phi_j^m dx + \sigma \int_{x_i}^{x_{i+1}} f^+(x,t_m) \phi_j^m dx & i = J + 1 
\end{cases} \\
D^2_i &= \begin{cases} 
(1 - \sigma) \int_{x_{i-1}}^{x_i} f^-(x,t_{m-1}) \phi_j^m dx & i \neq J, i \neq J + 1, i < J \\
(1 - \sigma) \int_{x_{i-1}}^{x_i} f^+(x,t_{m-1}) \phi_j^m dx & i \neq J, i \neq J + 1, i > J + 1 \\
(1 - \sigma) \int_{x_{i-1}}^{x_i} f^-(x,t_{m-1}) \phi_j^m dx + (1 - \sigma) \int_{x_i}^{x_{i+1}} f^+(x,t_{m-1}) \phi_j^m dx & i = J \\
(1 - \sigma) \int_{x_{i-1}}^{x_i} f^-(x,t_{m-1}) \phi_j^m dx + (1 - \sigma) \int_{x_i}^{x_{i+1}} f^+(x,t_{m-1}) \phi_j^m dx & i = J + 1 
\end{cases} 
\]

The matrices \( A^3 \) and \( B^4 \) correspond to the corrections, results of the \( \delta \)-Dirac function.

**NUMERICAL EXPERIMENTS**

As a test problem we consider

\[ u_r(x,t) - (\beta u_x(x,t))_x = -\delta(x - \zeta) K u(x,t) \quad (x,t) \in (0,1) \times (0,1), \]

with initial and boundary conditions

\[ u(x,0) = u_0(x) = \begin{cases} 
\cos(x/\sqrt{\beta^-}) & 0 \leq x \leq \zeta \\
\cos(\zeta/\sqrt{\beta^-}) & \sin(x/\sqrt{\beta^+}) \\
\sin(\zeta/\sqrt{\beta^+}) & \zeta < x \leq 1 
\end{cases} \]

\[ u(0,t) = u_L(t) = \frac{\exp(-t)}{\cos(\zeta/\sqrt{\beta^-})}, \quad u(1,t) = u_R(t) = \frac{\sin(1/\sqrt{\beta^+})\exp(-t)}{\sin(\zeta/\sqrt{\beta^+})}. \]
The function $K(t)$ for this problem is a constant $K = \sqrt{\beta^+ \tg\left(\frac{\zeta}{\sqrt{\beta^+}}\right)} + \sqrt{\beta^- \ctg\left(\frac{\zeta}{\sqrt{\beta^-}}\right)}$.

The jump conditions are:

$$[u(x,t)]_{x=\zeta} = u(\zeta^+,t) - u(\zeta^-,t) = 0,$$
$$[\beta u_x(x,t)]_{x=\zeta} = \beta^+ u_x(\zeta^+,t) - \beta^- u_x(\zeta^-,t) = K(t)u(\zeta,t) = Ku(\zeta,t).$$

The exact solution is

$$u(x,t) = \begin{cases} 
\cos(x/\sqrt{\beta^+}) \exp(-t), & 0 \leq x \leq \zeta \\
\cos(\zeta/\sqrt{\beta^+}) \\
\sin(x/\sqrt{\beta^+}) \exp(-t), & \zeta < x \leq 1.
\end{cases}$$

In Table 1 the results for the parameters $\sigma = 1/2, \zeta = \pi/6, K = \sqrt{\beta^+ \tg\left(\frac{\zeta}{\sqrt{\beta^+}}\right)} + \sqrt{\beta^- \ctg\left(\frac{\zeta}{\sqrt{\beta^-}}\right)}$ are presented. We choose two different cases for the discontinuous coefficients $\beta^- = 10, \beta^+ = 1$ and $\beta^- = 1, \beta^+ = 10$. The error of the numerical solution in maximum norm for different $N$ and $M$ is denoted by $\|e^M_N\|_\infty = \max\{|u(x, t) - z^h_m(x)|\}$, and the rate of convergence is by $\text{rate} = \log_2(\frac{\|e^M_N\|_\infty}{\|e^{2M}_N\|_\infty})$. The results confirm that the method is of second order on space and time for the case of $\sigma = 1/2$, when the method of weights is known as Crank-Nicolson method.

In Figure 1 the exact solution and the error of the numerical solution for $N = M = 40$ and $\beta^- = 1, \beta^+ = 10, \sigma = 1/2, \zeta = \pi/6$ are presented.

Table 1. The numerical results for $\sigma = 1/2, \zeta = \pi/6, K = \sqrt{\beta^+ \tg\left(\frac{\zeta}{\sqrt{\beta^+}}\right)} + \sqrt{\beta^- \ctg\left(\frac{\zeta}{\sqrt{\beta^-}}\right)}$

<table>
<thead>
<tr>
<th>N</th>
<th>M</th>
<th>$\beta^- = 10, \beta^+ = 1$</th>
<th>$\beta^- = 1, \beta^+ = 10$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>$|e^M_N|_\infty$</td>
<td>$\text{rate}$</td>
</tr>
<tr>
<td>5</td>
<td>5</td>
<td>0.000367</td>
<td>-</td>
</tr>
<tr>
<td>10</td>
<td>10</td>
<td>8.3325e-5</td>
<td>2.1418</td>
</tr>
<tr>
<td>20</td>
<td>20</td>
<td>1.6931e-5</td>
<td>2.2990</td>
</tr>
<tr>
<td>40</td>
<td>40</td>
<td>4.0763e-6</td>
<td>2.0543</td>
</tr>
<tr>
<td>80</td>
<td>80</td>
<td>1.0141e-6</td>
<td>2.0070</td>
</tr>
<tr>
<td>160</td>
<td>160</td>
<td>2.5325e-7</td>
<td>2.0015</td>
</tr>
<tr>
<td>320</td>
<td>320</td>
<td>6.3306e-8</td>
<td>2.0001</td>
</tr>
</tbody>
</table>
Many other numerical experiments with different values of the coefficients have been done. All of them confirm the following proposition:

**Proposition:** If the assumptions for the coefficients and functions are fulfilled, then the proposed IIFEM in the case $\sigma = 1/2$ is of second order both in space and time, i.e. for the error of the numerical solution of (9), (10) and (11) $z_m^h$ the estimate

$$\left\| z_m^h - u \right\|_{\infty} \leq C(h^2 + \tau^2)$$

holds, where the constant $C$ does not depend on $h$ and $\tau$.

**CONCLUSION**

In this work we investigate the application of the IIFEM for a parabolic problem with local own sources on some interface, embedding in the domain. For the numerical solution we use method of weights and FEM with special basic functions satisfying the jump conditions on the interface. Second order of convergence in the case $\sigma = 1/2$ is numerically proved. The theoretical proof of the proposition and application of ODE solvers of Matlab are object of our forthcoming work.

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ВЛОЖЕН ИНТЕРФЕЙСЕН МЕТОД НА КРАЙНИТЕ ЕЛЕМЕНТИ ЗА УРАВНЕНИЕ НА ДИФУЗИЯТА С ЛОКАЛЕН ИЗТОЧНИК

Иван Георгиев, Юрий Кандиларов
Русенски университет “Ангел Кънчев”

Резюме: В статията се разглежда уравнение на дифузията с локален собствен източник. Дефинирана е слаба формулировка на задачата и е приложен вложен интерфейсен метод на крайните елементи за численото решаване на проблема. При дискретизацията по време е използван метод на Роте с тела. След това са въведени специални базисни функции, които удовлетворяват условията на скока на решението и потока върху интерфейс. Представени са численi експерименти, които потвърждават втори ред на точност в максимална норма.

Ключови думи: вложен интерфейс, метод на крайните елементи, уравнение на дифузията, локални източници, метод на Роте
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